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## [MICRADS'20] Correction - Your submission has been accepted!

MICRADS'20 &lt;micradsmail@gmail.com&gt;

5 de febrero de 2020, 17:54

Responder a: micradsmail@gmail.com

Para: pfalban1@espe.edu.ec

Dear Author,

On behalf of the MICRADS'20 - The 2020 Multidisciplinary International Conference of Research Applied to Defense and Security, I am pleased to inform you that your submission 204, titled "Kinect and manipulator-based sample collection system for military robot" has been accepted for publication and oral presentation.

Please consider reviewers' comments below and the rules of edition strictly.

Papers in English will be published in Proceedings by Springer, in a book of its SIST series, and must follow the format standard from Springer available at <https://www.springer.com/us/authors-editors/conference-proceedings/conference-proceedings-guidelines>

Papers in Spanish or Portuguese will be published in a Special Issue of RISTI (Revista Ibérica de Sistemas e Tecnologias de Informação: <http://www.risti.xyz/>) and must follow the format standard from RISTI available at <http://www.risti.xyz/formato-es.doc>

Please prepare the camera-ready version of the paper, saved in both Word and PDF format. These files, for papers written in English, must be accompanied by the Consent to Publish form filled out, in a ZIP file, and uploaded until February 11 at the conference management system available at <http://www.aistic.org/micrads2020/oc20/openconf.php>.

Additionally, you also need to make your conference registration until February 18, in order your article can be published and presented. The payment of registrations from countries outside the European Union must be done by Debit or Credit card through our PayPal system.

Congratulations,

MICRADS'20 Team

<http://www.micrads.org/>[micradsmail@gmail.com](mailto:micradsmail@gmail.com)

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The paper is well written. Explain well the problem and methodology to solve it.

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This paper is objective and it has a lot data about its proposal military robot, so it is very important to understand the author goals.

This paper report to robots concepts, robot's elements and statistics calcs, parameters used and tools necessities to move the Anthropomorphic robot.

So this paper show a complete pratical study with a good rate of precision to capturate an object. I liked of demonstrate video that show the robot working.

But, author should correct the chapter 7 of references to chapter 5 and improve your conclusions.

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An important proposal based on kinect for a laboratory use is presented, but you must introduce it further into the theme of the conference (military). I clearly see that the work requires many improvements and I hope to make them for final publication.

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1. The summary does not show the problem
2. The introduction must be rewritten and extended.
3. There are parts of the text in another font size.

4. The tables are not in the proper format.
5. There are very small images that cannot be read.
6. Does not call for equations in the text.
7. Flowcharts cannot be read.
8. The conclusions should be extended.
9. I should use other bibliographic sources, from 9 to 15, they are very similar. Please include other related references such as:
  - \* Cooperative control of robotic spheres for tracking trajectories with visual feedback (Buele et al.)
  - \* Teleoperation and Remote Monitoring of a ScorBot ER-4U Robotic Arm in an Academic Environment (Franklin Salazar et al.)